

ICGT 2018:
CoReS: A Tool for Computing Core Graphs via
SAT/SMT Solvers

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Aim

Analyse the behaviour and verify the correctness of dynamically evolving systems.

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- Dynamic creation and deletion of objects
- Variable topologies
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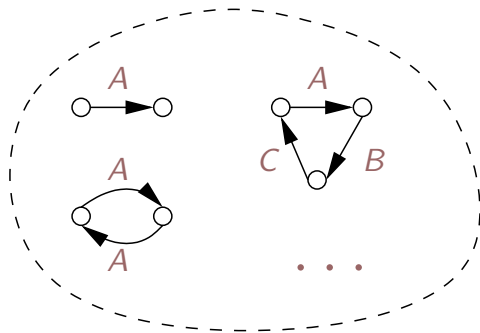
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Trade-off: More complex modeling language \rightsquigarrow harder analysis.

Overview

In this Talk

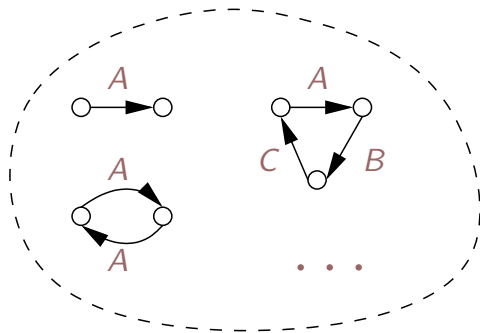
Specify (possibly infinite) sets of graphs by finite graphs and compute their corresponding minimal representation.



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Specify (possibly infinite) sets of graphs by finite graphs and compute their corresponding minimal representation.



Solving a *subtask* from our [predecessor paper](#) (ICGT 2017)

Contents

Background and Preliminaries (Exposition)

- Specifying Graph Languages using Type Graphs
- Retracts and Cores

Core Computation via SAT/SMT Encodings (Rising Action)

- Retract Morphism Properties
- Core Computation Encodings

CoReS (Peripety)

- Tool Demo
- Runtime Results

Final Remarks (Dénouement)

Part I

Background and Preliminaries

The Basic Framework of Type Graphs

We started by studying type graphs as a specification language.

Type Graph Language

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$$\mathcal{L}(T) = \{G \mid \text{there exists a morphism } \varphi: G \rightarrow T\}$$

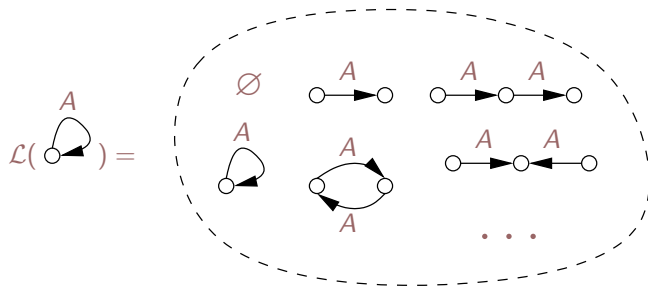
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- They are simple.
- Other formalisms are based on type graphs (e.g., abstract graphs that use type graphs with additional annotations)
- Refine/Extend this basic formalism and analyse the properties.

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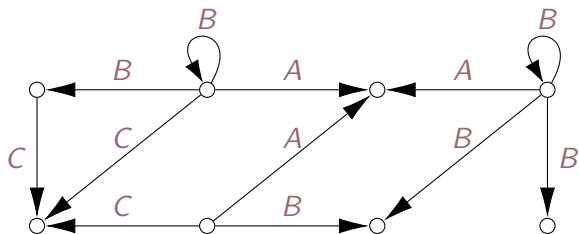
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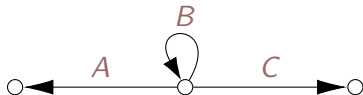
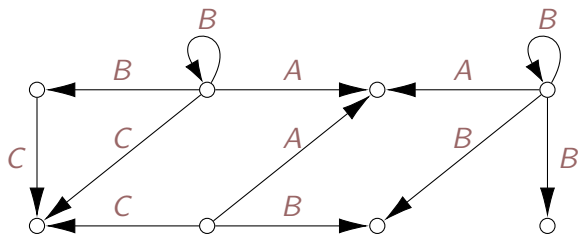
Today's aim:

Efficiently minimize the type graph without changing its language.

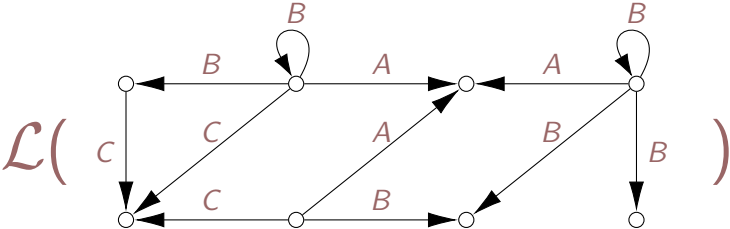
Minimization



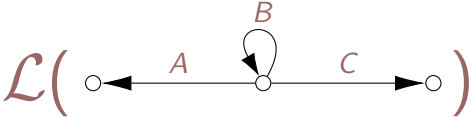
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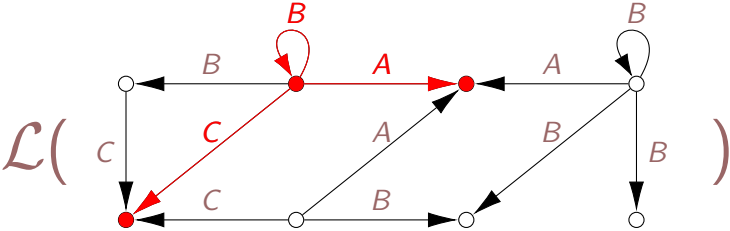
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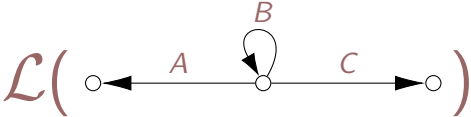
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Retracts and Core Graphs

A subgraph T' of a graph T for which there exists a morphism $\varphi: T \rightarrow T'$ is called a **retract** of T .

If a graph has no proper retracts itself, it is called **core** graph. (Nešetřil, Tardif).

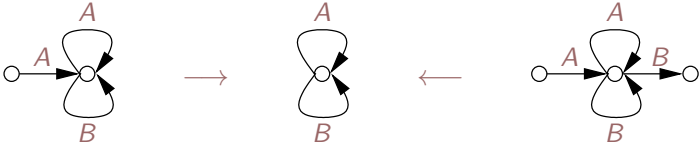
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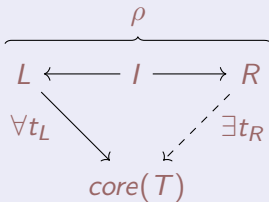
Core

Invariant Checking

Let T be a graph and $core(T)$ be its core.

Closure under rewriting

$\mathcal{L}(T)$ is closed under application of $\rho \iff$

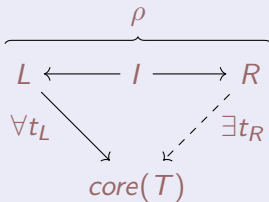


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Question: How can we efficiently compute the core graph?

Part II


Core Computation via SAT/SMT Encodings

The Problem

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Retract Morphism Problem

Given a graph G . Does there exist a non-surjective endomorphism $\varphi': G \rightarrow G$ with $\varphi'|_H = id_H$ where $H = \text{img}(\varphi')$?

SMT Solver

Satisfiability modulo theories (SMT) problem is a decision problem for logical formulas with respect to combinations of background theories expressed in classical **first-order logic**.

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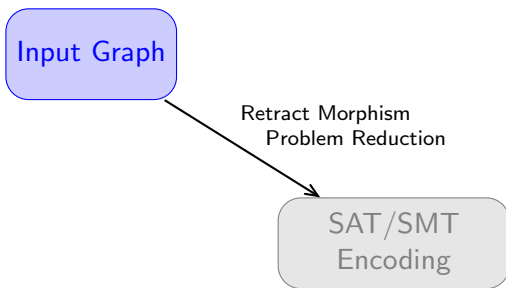
Example

```
(declare-const x Int)           |  $x, y \in \text{Int}$   
(declare-const y Int)  
(assert (= (- x y) (+ x (- y) 1))) |  $x - y = x - y + 1$   
(check-sat)
```

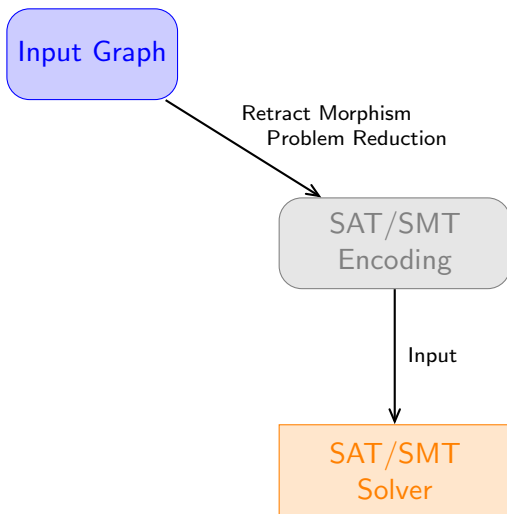
Core Computation in a Nutshell

Input Graph

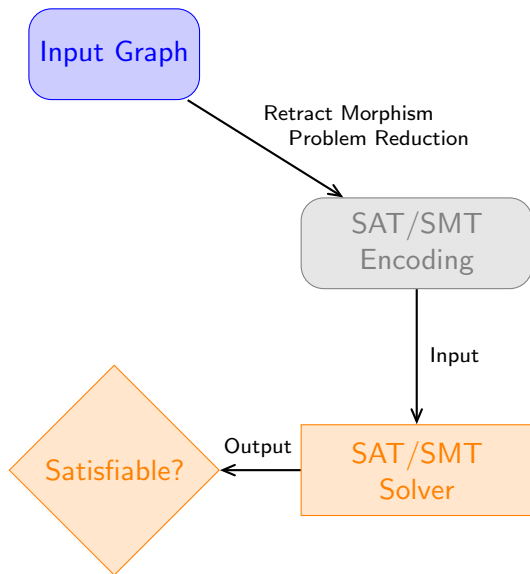
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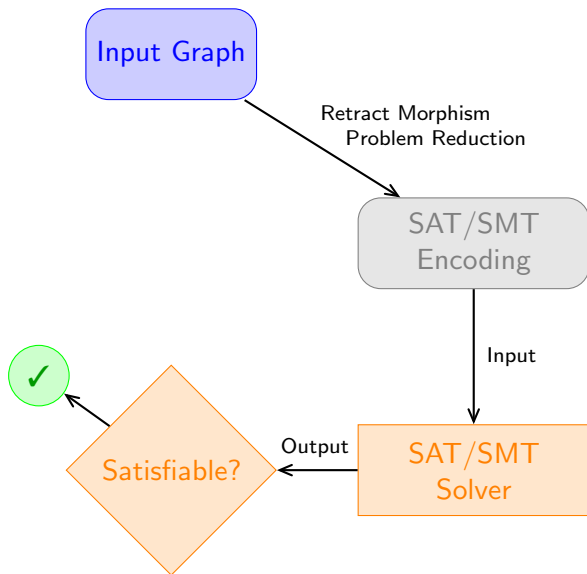
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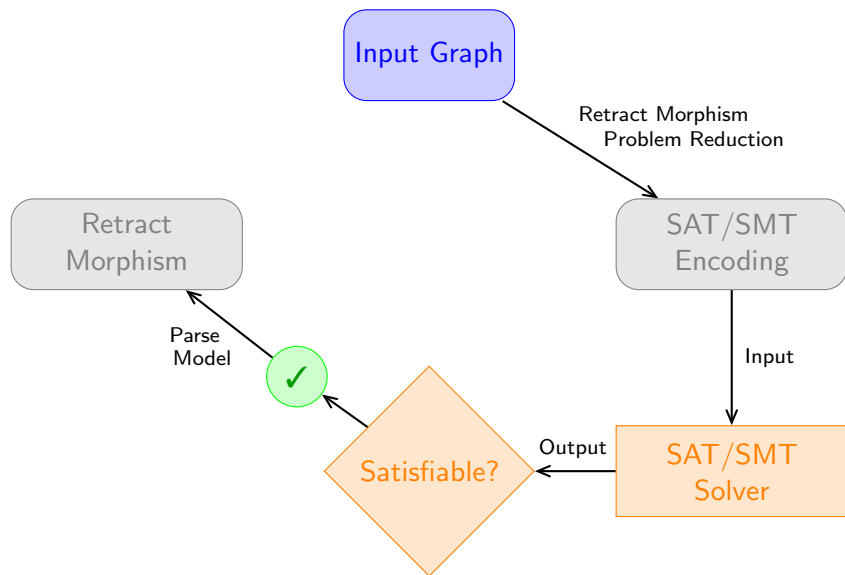
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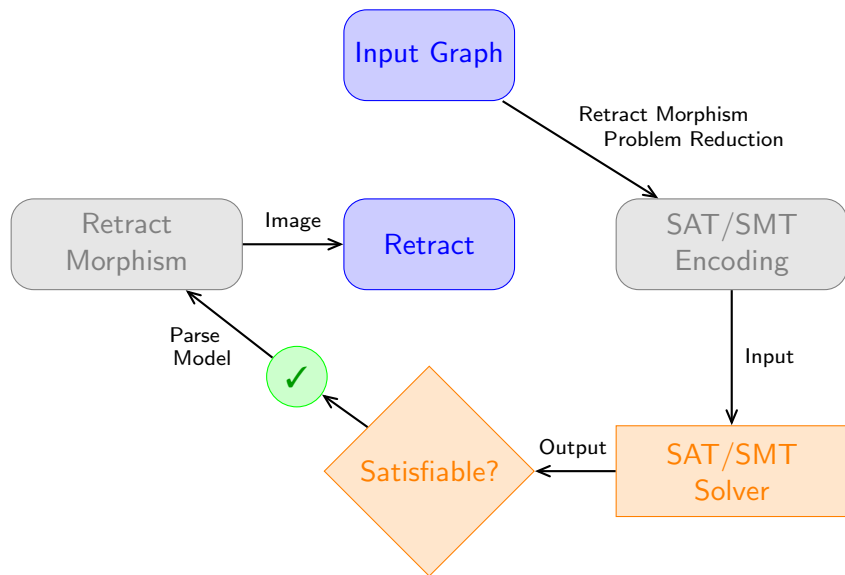
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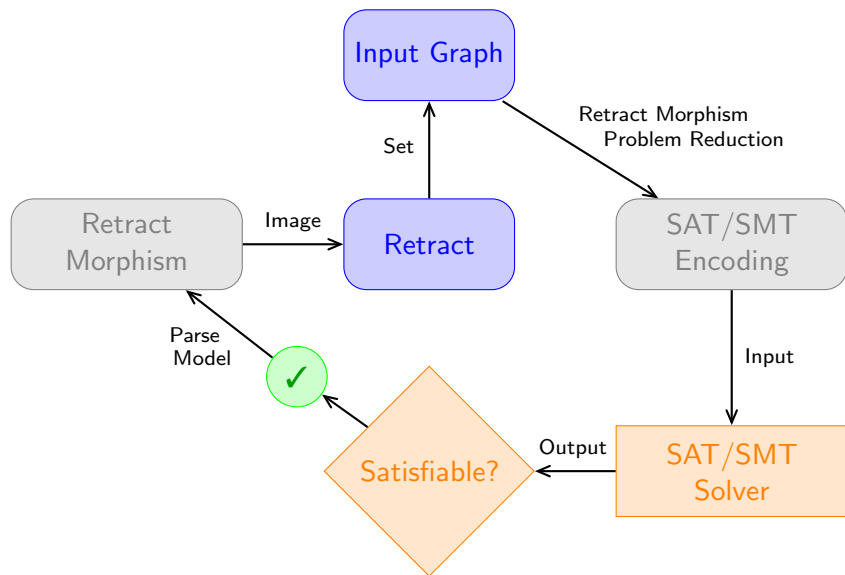
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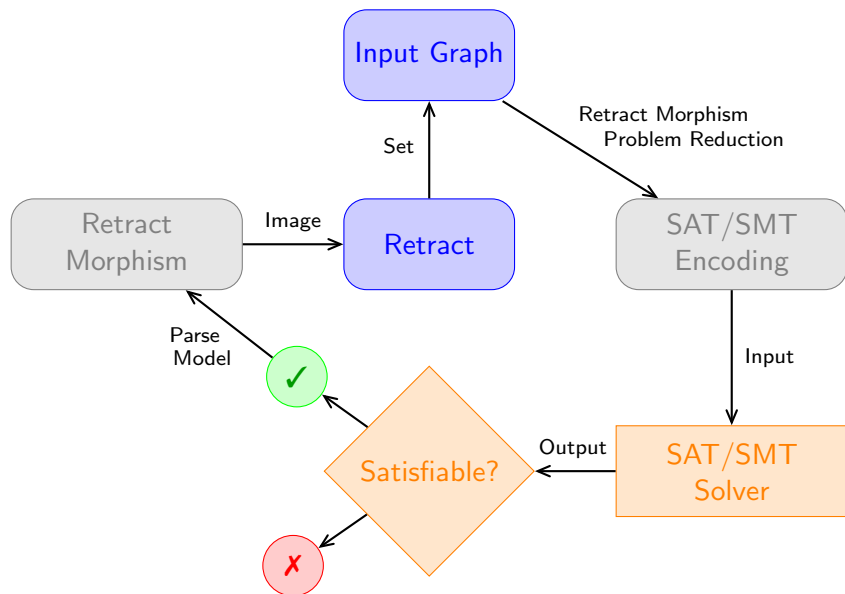
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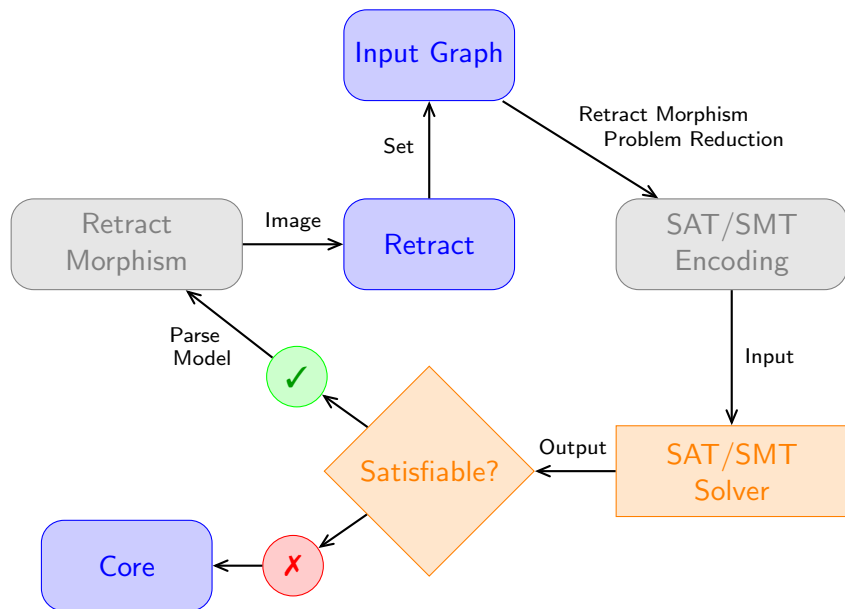
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The morphism φ needs to be **structure preserving**, i.e.

$$src(\varphi_E(e)) = \varphi_V(src(e)) \quad tgt(\varphi_E(e)) = \varphi_V(tgt(e)) \quad lab(\varphi_E(e)) = lab(e)$$

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3) Retract property:

The morphism φ restricted on its image is an **identity morphism**, i.e.

$$\varphi|_{img(\varphi)} = id_{img(\varphi)}$$

SMT-LIB2 Encoding of Retract Morphism Properties

Initialize the components of the input $G = (V, E, src, tgt, lab)$:

(declare-datatypes () ((V v1 ... vN))) | ($V = \{v_1, \dots, v_n\}$)

(declare-datatypes () ((E e1 ... eM))) | ($E = \{e_1, \dots, e_m\}$)

(declare-datatypes () ((L A ...))) | ($\Lambda = \{A, \dots\}$)

(declare-fun src (E) V) | $src: E \rightarrow V$


(declare-fun tgt (E) V) | $tgt: E \rightarrow V$

(declare-fun lab (E) L) | $lab: E \rightarrow \lambda$

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<code>(declare-datatypes () ((L A ...)))</code>	$(\Lambda = \{A, \dots\})$
<code>(declare-fun src (E) V)</code>	$src: E \rightarrow V$
<code>(declare-fun tgt (E) V)</code>	$tgt: E \rightarrow V$
<code>(declare-fun lab (E) L)</code>	$lab: E \rightarrow \lambda$

For instance the graph  can be encoded in the following way:

<code>(assert (= (src e1) v1))</code>	$src(e_1) = v_1$
<code>(assert (= (tgt e1) v2))</code>	$tgt(e_1) = v_2$
<code>(assert (= (lab e1) A))</code>	$lab(e_1) = A$

SMT-LIB2 Encoding of Retract Morphism Properties

Next, we specify the constraints for the morphism $\varphi: G \rightarrow G$:

1) Graph morphism property

<code>(declare-fun vphi (V) V)</code>	$ \varphi_V: V \rightarrow V$
<code>(declare-fun ephi (E) E)</code>	$ \varphi_E: E \rightarrow E$
<code>(assert (forall ((e E)) (= (src (ephi e)) (vphi (src e)))))</code>	$ \text{src}(\varphi_E(e)) = \varphi_V(\text{src}(e))$
<code>(assert (forall ((e E)) (= (tgt (ephi e)) (vphi (tgt e)))))</code>	$ \text{tgt}(\varphi_E(e)) = \varphi_V(\text{tgt}(e))$
<code>(assert (forall ((e E)) (= (lab (ephi e)) (lab e))))</code>	$ \text{lab}(\varphi_E(e)) = \text{lab}(e)$

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(assert (forall ((e E)) (= (lab (ephi e)) (lab e))))	$lab(\varphi_E(e)) = lab(e)$

2) Subgraph property

(assert (exists ((v1 V)) not(exists ((v2 V)) (= v1 (vphi v2)))))	$\exists v_1 \in V \neg \exists v_2 \in V:$ $v_1 = \varphi_V(v_2)$
--	---

SMT-LIB2 Encoding of Retract Morphism Properties

We need to specify that the retract property $\varphi|_{\text{img}(\varphi)} = \text{id}_{\text{img}(\varphi)}$ holds. We rephrase this requirement in the following way:

$$\forall x \in G \left((\exists y \in G (\varphi(y) = x)) \implies \varphi(x) = x \right)$$

Every element in the image of φ is part of the retract and therefore always has to be mapped to itself.

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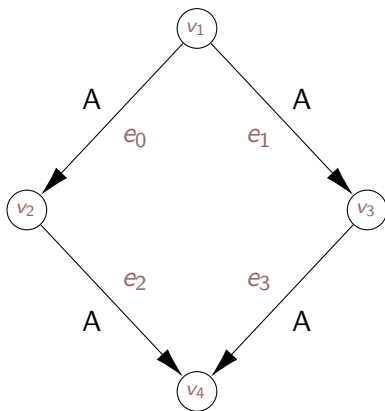
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3) Retract property

```
(assert (forall ((v1 V)) (= > (exists ((v2 V)) (= v1 (vphi v2))) (= v1 (vphi v1))))))
```

```
(assert (forall ((e1 E)) (= > (exists ((e2 E)) (= e1 (ephi e2))) (= e1 (ephi e1))))))
```

Example Graph



SAT Encoding of Retract Morphism Properties

The SAT encoding is more tedious to achieve.

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Remove parallel edges from the type graph in a preprocessing step

↪ Find a **node mapping** describing the retract since the corresponding edge mappings can be derived from it.

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Our set of **atomic propositions** \mathcal{A} has size $|\mathcal{A}| = |V \times V|$.

For a pair of nodes $(x, y) \in V \times V$ we use **Ax-y** with

$$\mathcal{A} \ni Ax-y \equiv \text{true} \text{ iff } \varphi_V(x) = y \text{ holds.}$$

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The node mapping must be a function.

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For a pair of nodes $(x, y) \in V \times V$ we use A_{x-y} with

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The node mapping must be a function.

Additional requirement

$$\bigwedge_{x \in V} \bigvee_{y \in V} \left(A_{x-y} \wedge \left(\bigwedge_{z \in V \setminus \{y\}} \neg A_{x-z} \right) \right) \quad | \quad \forall x \exists ! y \varphi_V(x) = y$$

SAT Encoding of Retract Morphism Properties

1) Graph morphism property

$$\bigwedge_{e \in E} \bigvee_{e' \in E_{lab(e)}} \left((A_{src(e)-src(e')}) \wedge (A_{tgt(e)-tgt(e')}) \right)$$

2) Subgraph property

$$\bigvee_{x \in V} \left(\bigwedge_{y \in V} \neg A_{y-x} \right) \quad | \exists x \forall y \varphi(y) \neq x$$

3) Retract property

$$\bigwedge_{x \in V} \left(\left(\bigvee_{y \in V} A_{y-x} \right) \Rightarrow A_{x-x} \right) \quad | \varphi|_H = id_H$$

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The derivation of the formulas above is given in our paper.

Part III

CoReS

(Computation of Retracts encoded SAT/SMT)

Experiments

The encodings were tested on 125 random graphs consisting of

- a fixed number of nodes $|V|$.
- a fixed number of available edge labels $|\Lambda|$.
- a fixed probability ρ for an edge to exist.

SAT (Limboole) vs SMT (Z3)

		$\rho \cdot V \cdot \Lambda $									
		0.5		0.8		1.0		1.2		1.5	
$ V $	$ \Lambda $	SAT	SMT	SAT	SMT	SAT	SMT	SAT	SMT	SAT	SMT
16	1	.075	.116	.078	.344	.078	.733	.071	1.17	.070	3.01
	2	.067	.155	.096	.463	.080	1.12	.079	2.11	.078	4.21
	3	.063	.172	.100	.548	.074	1.14	.071	2.02	.073	4.09
32	1	.301	.620	.306	4.58	.396	12.4	.424	27.4	.500	67.5
	2	.389	1.08	.407	7.27	.415	14.9	.447	37.6	.450	121
	3	.322	1.52	.383	5.27	.365	19.3	.391	40.3	.382	110

Final Remarks

Contribution:

- **Investigation of encodings for core computations:**
Analysis and encoding of needed properties in SAT/SMT.
- **Benchmarks:**
Trade-off between readability and performance.

Tool support:

- **CoReS:**
Automatically compute core graphs via SAT/SMT encodings.

Features:

- GUI mode for visualized core computations.
- Integrable and executable standalone command line interface.
- User-manual and source code (Python) available on GitHub:
<https://github.com/mnederkorn/CoReS>

Thank You
for your attention

Part IV

Additional Material

Invariant checking

Closure under Rewriting

Question: Given T and a (DPO) GTS rule $r = (L \leftarrow I \rightarrow R)$.
Does $Post_{\{r\}}(\mathcal{L}(T)) \subseteq \mathcal{L}(T)$ hold?

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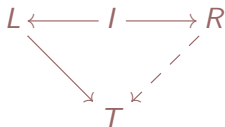
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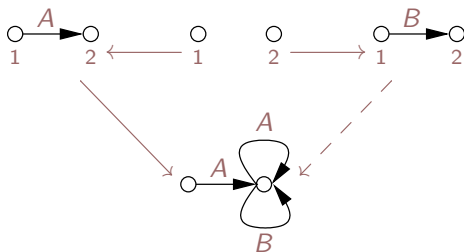
$Post_{\{r\}}(\mathcal{L}(T))$ can **not** be computed...

Sufficient condition: Check whether for each morphism $L \rightarrow T$ there exists a morphism $R \rightarrow T$ such that the diagram below commutes. This implies closure under rewriting.



The missing piece

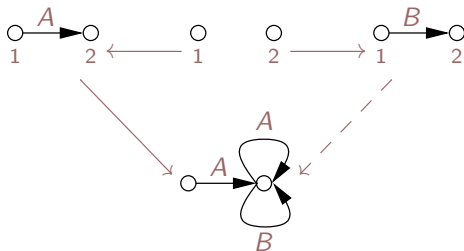
This is **not** an if-and-only-if condition. Counterexample:



However, the type graph represents *all* graphs with *A*- and *B*-labelled edges and is hence closed under rewriting.

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Solution: We obtain an if-and-only-if condition if we require that the type graph *T* is a core!

Experiments

Additional SAT runtimes

$ V $	$ \Lambda $	$\rho \cdot V \cdot \Lambda $										
		0.5	0.6	0.7	0.8	0.9	1.0	1.1	1.2	1.3	1.4	1.5
24	1	.462	.595	.309	.333	.351	.359	.388	.476	.371	.589	.354
	2	.337	.356	.548	.587	1.29	.623	.685	.685	.511	.739	.497
	3	.410	.401	1.00	.460	.456	.871	.450	.490	1.60	.615	.574
32	1	.619	.828	.901	1.17	1.11	.85	.973	1.29	.986	1.01	1.53
	2	.683	.809	.792	.988	1.03	1.27	1.04	1.13	1.23	1.22	1.23
	3	1.13	1.01	.821	.819	1.16	.937	1.10	1.05	1.87	1.27	1.20
48	1	2.39	2.62	3.27	3.15	4.45	5.18	5.34	7.18	5.01	5.93	6.24
	2	1.83	1.83	3.23	3.68	3.97	3.98	4.75	5.47	4.98	5.02	5.37
	3	2.35	2.57	3.06	3.25	3.59	3.94	3.88	4.17	4.28	5.33	4.96
64	1	6.63	8.65	12.0	12.7	19.4	21.9	21.2	26.2	22.5	22.1	26.0
	2	4.04	5.91	6.73	10.9	10.3	14.9	15.2	15.2	15.4	15.7	18.4
	3	4.53	5.60	7.22	8.96	9.02	11.0	10.6	12.0	12.7	11.9	12.1
96	1	37.5	49.8	92.8	125	123	165	140	163	193	152	194
	2	28.6	49.9	59.7	85.5	98.9	102	107	115	127	111	116
	3	23.7	36.7	50.4	60.6	52.0	51.8	48.8	52.6	49.0	44.0	46.6